



LABORATORY FOR
**Computational
Sensing + Robotics**

MASTER OF SCIENCE IN
ENGINEERING IN ROBOTICS

GRADUATE STUDENT ADVISING MANUAL

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JOHNS HOPKINS
UNIVERSITY

CONTENTS

CONTENTS.....	2
WELCOME	4
MSE DEGREE REQUIREMENTS	5
Seminar Course Requirement	5
Additional Required Courses	6
MSE Core Courses	6
MSE Degree Track Requirements	7
Automation Science and Engineering Track	7
BioRobotics Track.....	8
Control and Dynamical Systems Track.....	8
Medical Robotics Track	9
Perception and Cognitive Systems Track.....	10
General Robotics Track	11
MSE Degree Electives Courses	12
Master’s Essay/Internship Option	13
ADVISING	13
MSE Academic Advising	13
MSE Essay Advising	14
MSE Internship Advising	15
Graduate Student Annual Reviews	16
GRADUATION	17
Academic Deadlines	17
To Graduate	17
ACADEMIC POLICIES.....	18
Academic Performance Requirements	18
Audit Courses	18
Double Counting	18
Duration (Time to Completion Limit).....	19
Ethics.....	19
Graduate Research Courses.....	20
Laboratory Safety.....	20



Notice of Non-Discriminatory Policy.....	20
Residency Requirements	21
Transfer Courses	21
WSE Engineering Management Courses.....	21
WSE Engineering for Professionals (EP) Courses	21
Additional policies.....	21
RESOURCES	22
Center for Leadership Education	22
Financial Aid	22
Graduate Student Organizations	22
Information Technology.....	22
International Office.....	22
Libraries.....	23
Security	23
Student Disability Services	23
Student Employment	24
Writing Center.....	24
LCSR FACULTY	25
LCSR ADMINISTRATIVE STAFF	27
Important Education Contacts.....	27



WELCOME

Welcome to the Robotics MSE program in the Laboratory for Computational Sensing and Robotics (LCSR)

This manual is designed to serve as a guide for graduate students in LCSR to work more effectively and to describe the basic academic requirements for the Robotics MSE degree. This manual covers policies, rules, and procedures, and offers suggestions regarding our program. The detailed planning of an academic program, such as choosing courses and the like must be done with the guidance of the academic advisor. Please note that like any complex program, the Robotics MSE is a living program and while the MSE manual is as accurate as possible, it is important that you clarify any unclear issues with your academic advisor and/or Robotics Academic Manager, Alison Morrow. Also, please note it is the student's responsibility to read the entire MSE advising manual, and to take complete responsibility for fulfilling the academic and other graduate requirements. Your Advisor and the Robotics Academic Staff are here to help, answer questions, and offer suggestions, but ultimately you must take ownership in your own degree program.



MSE DEGREE REQUIREMENTS

Course Option: 10 full-time academic courses (each class at least 3 credits, e.g. not seminars, safety training, etc.).

Research Essay/Internship Option:

Essay: 8 full-time academic courses (each class at least 3 credits, e.g. not seminars, safety training, etc.) and a Master's Essay supervised by a WSE faculty member who has been approved by the Robotics MSE Curriculum Committee to serve as an academic advisor. (See the Essay Option section for more information.)

Internship¹: 8 full-time academic courses (each class at least 3 credits, e.g. not seminars, safety training, etc.) and an Internship with a Report supervised by a WSE faculty member who has been approved by the Robotics MSE Curriculum Committee to serve as an academic advisor. (See the Internship Option section for more information.)

At least 6 of these courses must be at the graduate level as defined by the offering department/center. All courses counted toward the MSE degree requirements must be at the 400 level or above. Any dual listed courses (e.g. listed at both the 600 and 400 level) must be taken at the 600 level. All courses counting towards the foundation, track, or elective requirements must be for a letter grade (e.g. no pass/fail). Any exceptions must be approved in writing by your academic advisor and the LCSR Education Director. Non-credit and one-credit courses such as the weekly seminar courses offered by LCSR may not count toward this course requirement.

If you are a combined student (i.e. graduated with your undergraduate degree from JHU) who took required courses at the 400 level during your undergraduate course work, the classes can count as fulfilling the requirement. You will still need to fulfill the requirement of at least six (6) 600 level courses or above to complete the degree.

Seminar Course Requirement

Students are required to register for the following one-credit weekly robotics research seminar course every term in which they are in full-time residency. If you have changed to part-time status, please talk to your academic staff about this requirement.

The course number is: 620.745 Seminar in Computational Sensing and Robotics

¹ Internship Option is pending final review of the Whiting School of Engineering's Graduate Committee.



Additional Required Courses

Every effort should be made to take these within the first semester.

Graduate Orientation and Academic Ethics (EN.500.603)

Online tutorial required for all incoming MSE students. Auto-enrolled in first semester. This course includes required Opioid training and Title IX training.

Research Laboratory Safety (EN.500.601)

Required for all incoming MSE students. It is recommended that this course be taken in the student's first semester. It is required that the student take it by the end of their first year.

Responsible Conduct of Research course

AS.360.624 (online) required for all incoming MSE students. Instructions for registering:

<https://engineering.jhu.edu/research/resources-policies-forms/online-training-course-responsible-conduct-of-research/>. **IMPORTANT: MAKE SURE TO REGISTER WITH YOUR JHU EMAIL ADDRESS. Doing otherwise will cause issues.**

OR

AS.360.625 (in-person) may be required for certain research projects.

Additional information about the Responsible Conduct of Research course can be found here:

<https://engineering.jhu.edu/research/resources-policies-forms/responsible-conduct-of-research-training-for-students-and-postdoctoral-fellows-revised-spring-2020/>

MSE Core Courses

(2 courses and a seminar)

Two first year graduate level courses form the core of the Robotics MSE program. These courses can be taken in either order. It is strongly recommended to not take both classes in the same semester. Both classes are required.

601.663 Algorithms for Sensor-Based Robotics (3 credits)

This course surveys the development of robotic systems for navigating in an environment from an algorithmic perspective. It will cover basic kinematics, configuration space concepts, motion planning, and localization and mapping. It will describe these concepts in the context of the ROS software system, and will present examples relevant to mobile platforms, manipulation, robotics surgery, and human-machine systems.

530.646 Robot Devices, Kinematics, Dynamics, and Control (4 credits)

Graduate-level introduction to the mechanics of robotic systems with emphasis on the mathematical tools for kinematics and dynamics of robot arms and mobile robots. Topics include the geometry and mathematical representation of rigid body motion, forward and inverse kinematics of articulated mechanical arms, trajectory generation, manipulator dynamics, actuation, and design issues, manipulator control, and additional special topics. Recommended course background: multivariable integral and differential calculus, classical physics, linear algebra, ordinary differential equations. Programming: Knowledge of the Matlab programming language including data input/output, 1-D and 2-D arrays, and user-defined function calls. Students with experience with these language elements



in other programming languages (C, C++, Python, Java, etc.) should be able to self-tutor themselves in the Matlab language as part of the programming exercises.

MSE Degree Track Requirements

(4 Courses)

Tracks consist of course sequences that provide the student with strength in a specific area. Track requirements are listed below. Other courses may be substituted only with the written approval of both the student's academic advisor and the Robotics Education Director. Many of these courses are offered in multiple departments – alternative course numbers for the same class are acceptable substitutions. Please confirm with your advisor that you have signed up for the correct courses. Not all courses will necessarily be offered each semester or each year. **Note: Students should discuss their academic plan with their advisor. Specific choices are subject to approval of plan by advisor.** Courses counted towards the track requirement may not be used to satisfy the elective requirement. *Note: at most two EP Courses (eg. 535.xxx.xx) can be counted toward the MSE with prior approval of advisor.*

Automation Science and Engineering Track

Choose four (4) courses from the following list.

Starred and bolded choices are strongly recommended.

- 520.448 Electronics Design Lab ***
- 520.640 Machine Intelligence on Embedded Systems
- 520.657 Product Design Lab
- 520.662/520.663 Leading Innovation Design Team
- 520.637 Foundations of Reinforcement Learning
- 520.738 Advanced Electronic Design Lab
- 520.773 Advanced Topics in Microsystem Fabrication
- 530.414 Computer-Aided Design***
- 530.420 Robot Sensors/Actuators
- 530.421 Mechatronics
- 530.495 Microfabrication Laboratory
- 530.623 Design of Marine Robots
- 530.663 Robot Motion Planning
- 530.641 Statistical Learning for Engineers
- 530.645 Kinematics
- 530.649 System Identification
- 530.653 Advanced Systems Modeling
- 530.666 Magnetically Actuated and MRI Compatible Robots
- 535.427 Computer Aided Design* (NOT to be counted if 530.414 is taken)**
- 535.459 Manufacturing Systems Analysis***
- 535.473 Mechanized Assembly: Hardware and Algorithms
- 535.460 Precision Mechanical Design***
- 553.761 Nonlinear Optimization 1
- 553.762 Nonlinear Optimization 2
- 553.663 Network Models in Operations Research
- 601.661 Computer Vision



BioRobotics Track

Choose four (4) courses from the following list.

Starred and bolded choices are strongly recommended.

- 520.621 Introduction to Nonlinear Systems
- 530.485 Physics and Feedback in Living Systems
- 530.649 System Identification
- 530.668 Locomotion Mechanics: Fundamentals***
- 530.669 Locomotion Mechanics: Recent Advances***
- 530.676 Locomotion Dynamics and Control***
- 530.691 Haptic Interface Design for Human-Robot Interaction
- 580.630 Theoretical Neuroscience
- 580.742 Neural Implants and Interfaces
- 530.616/580.616/520.601 Introduction to Linear Systems

Control and Dynamical Systems Track

Choose four (4) courses from the following list.

Starred and bolded choices are strongly recommended.

- 520.621 Introduction to Nonlinear Systems***
- 520.629 Networked Dynamical Systems
- 520.633 Intro to Robust Control
- 520.654 Control System Design
- 520.637 Foundations of Reinforcement Learning
- 530.470 Space Vehicle Dynamics and Control
- 530.603 Applied Optimal Control
- 530.623 Design of Marine Robots
- 530.624 Dynamics of Robots and Spacecraft
- 530.641 Statistical Learning for Engineers
- 530.647 Adaptive Systems
- 530.649 System Identification
- 530.653 Advanced Systems Modeling
- 530.654 Advanced Systems Modeling II
- 530.668 Locomotion Mechanics: Fundamentals
- 530.676 Locomotion Dynamics and Control
- 530.678 Nonlinear Control and Planning in Robotics***
- 530.696 Learning Based Control for Robotics
- 530.761 Mathematical Methods of Engineering I
- 553.792 Matrix Analysis
- 553.797 Intro to Control Theory and Optimal Control
- 530.616/580.616/520.601 Introduction to Linear Systems Theory***



Medical Robotics Track

Two (2) required courses and two (2) courses from the following list.

Required for the track:

- 601.655 Computer-Integrated Surgery 1
- 601.656 Computer-Integrated Surgery 2

Choose two (2) of the following:

- 520.613 Adv Topics in Optical Medical Imaging
- 520.623 Medical Image Analysis
- 520.631 Ultrasound and Photoacoustic Beamforming
- 520.632 Medical Imaging Systems
- 530.420 Robot Sensors/Actuators
- 530.663 Robot Motion Planning
- 530.666 Magnetically Actuated and MRI Compatible Robots
- 530.691 Haptic Interface Design for Human-Robot Interaction
- 530.721 Medical Robotics System Design
- 530.761 Mathematical Methods of Engineering I
- 580.673 Magnetic Resonance in Medicine
- 580.679 X-ray Imaging and Computed Tomography
- 580.684 Ultrasound Imaging: Theory and Applications
- 580.693 Imaging Instrumentation
- 580.740 Surgery for Engineers
- 601.653 Applications of Augmented Reality
- 601.654 Augmented Reality
- 601.661 Computer Vision
- 601.676 Machine Learning: Data to Models
- 580.683 Nuclear Medicine Imaging



Perception and Cognitive Systems Track

Choose four (4) courses from the following list.

Starred and bolded choices are strongly recommended.

- 520.614 Image Processing and Analysis
- 520.612 Machine Learning for Signal Processing
- 520.615 Image Process and Analysis II
- 520.637 Foundations of Reinforcement Learning
- 520.638 Deep Learning
- 520.641 Neuromorphic Circuits and Systems
- 520.646 Wavelets and Filter Banks
- 520.665 Machine Perception
- 530.420 Robot Sensors/Actuators
- 530.421 Mechatronics
- 530.641 Statistical Learning for Engineers
- 530.663 Robot Motion Planning
- 530.691 Haptic Interface Design for Human-Robot Interaction
- 530.696 Learning Based Control for Robotics
- 530.707 Robot System Programming
- 553.693 Mathematical Image Analysis
- 553.761 Nonlinear Optimization 1
- 553.762 Nonlinear Optimization 2
- 580.630 Theoretical Neuroscience
- 580.639 Models of the Neuron
- 580.742 Neural Implants and Interfaces
- 601.653 Applications of Augmented Reality
- 601.654 Augmented Reality
- 601.661 Computer Vision***
- 601.664 Artificial Intelligence***
- 601.675 Machine Learning
- 601.682 Machine Learning: Deep Learning
- 601.686 Machine Learning: AI System Design and Development
- 601.691 Human-Robot Interaction
- 601.760 FFT in Graphics and Vision
- 601.783 Vision as Bayesian Inference
- AS.050.675 Probabilistic Models of the Visual Cortex



General Robotics Track

Choose four (4) courses from the following list.

520.621	Intro to Nonlinear Systems		530.668	Locomotion Mechanics: Fundamentals
520.633	Intro to Robust Control		530.669	Locomotion Mechanics: Recent Advances
520.637	Foundations of Reinforcement Learning		530.676	Locomotion Dynamics and Control
520.654	Control System Design		530.678	Nonlinear Control and Planning in Robotics
520.662/ 520.663	Leading Innovation Design Team		530.691	Haptic Interface Design for Human-Robot Interaction
520.665	Machine Perception		530.707	Robot Systems Programming
530.414	Computer-Aided Design		530.721	Medical Robotics System Design
530.420	Robot Sensors/Actuators		530.761	Mathematical Methods of Engineering I
530.421	Mechatronics		553.761	Nonlinear Optimization 1
530.470	Space Vehicle Dynamics and Control		553.762	Nonlinear Optimization 2
530.603	Applied Optimal Control		553.792	Matrix Analysis
530.613	Mechanical Engineering Master's Design I		553.797	Intro to Control Theory and Optimal Control
530.614	Mechanical Engineering Master's Design II		601.653	Applications of Augmented Reality
530.623	Design of Marine Robots		601.654	Augmented Reality
530.624	Dynamics of Robots and Spacecraft		601.655	Computer-Integrated Surgery 1
530.663	Robot Motion Planning		601.656	Computer-Integrated Surgery 2
530.641	Statistical Learning for Engineers		601.661	Computer Vision
530.645	Kinematics		601.664	Artificial Intelligence
530.647	Adaptive Systems		601.675	Machine Learning
530.648	Group Theory in Engineering Design		601.682	Machine Learning: Deep Learning
530.649	System Identification		601.691	Human-Robot Interaction
530.653	Advanced Systems Modeling		530.616/ 580.616/ 520.601	Introduction to Linear Systems Theory
530.654	Advanced Systems Modeling II			
530.666	Magnetically Actuated and MRI Compatible Robots			



MSE Degree Electives Courses

(Four (4) Courses or Two (2) Courses + MSE Essay)

Any engineering or quantitative graduate course as approved by your advisor and subject to the degree requirement limitations, including but not limited to: all courses counted toward the MSE degree requirements must be at the 400 level or above. Any dual-listed courses (i.e. listed at both the 600 and 400 level) must be taken at the 600 level. Any exceptions must be approved in writing by your academic advisor. All electives must be at least 3 credits. Electives include, **but are not limited to**, the following:

520.623	Medical Image Analysis		530.669	Locomotion Mechanics: Recent Advances
520.632	Medical Imaging Systems		530.676	Locomotion Dynamics and Control
520.640	Machine Intelligence on Embedded Systems		530.678	Nonlinear Control and Planning in Robotics
520.657	Product Design Lab		530.707	Robot Systems Programming
520.662/ 520.663	Leading Innovation Design Team		530.761	Mathematical Methods of Engineering I
520.683	Bio-Photonics Laboratory		553.761	Nonlinear Optimization 1
520.691	CAD Design of Digital VLSI Systems I		553.762	Nonlinear Optimization 2
520.773	Advanced Topics in Microsystem Fabrication		553.663	Network Models in Operations Research
530.414	Computer-Aided Design		601.691	Human-Robot Interaction
530.420	Robot Sensors/Actuators		601.655	Computer Integrated Surgery 1
530.421	Mechatronics		601.656	Computer Integrated Surgery 2
530.495	Microfabrication Lab		601.661	Computer Vision
530.624	Dynamics of Robots and Spacecraft		601.664	Artificial Intelligence
530.628	Nonlinear Dynamical Systems		601.675	Machine Learning
530.641	Statistical Learning for Engineers		601.682	Machine Learning: Deep Learning
530.647	Adaptive Systems		601.686	Machine Learning: AI System Design and Development
530.649	System Identification		601.760	FFT in Graphics and Vision
530.653	Advanced Systems Modeling		601.783	Vision as Bayesian Inference
530.668	Locomotion Mechanics: Fundamentals			

Courses counted towards the track requirement may not be used to satisfy the elective requirement.



Master's Essay/Internship Option²

Many students elect to take the Course Option. In some cases, with the approval of a research advisor, the Essay Option may be used to fulfill the MSE Robotics degree requirements. In the Course Option, ten (10) courses must be taken as articulated above. For the Essay and Internship Options, eight (8) courses must be taken, and research must be performed leading to a formal MSE Essay or Internship Report. Degree Track requirements are the same for both the Course and Essay Options. For more information on the policy and procedures for the Essay or Internship Options, please see the advising section below.

ADVISING

MSE Academic Advising

All incoming MSE students will be assigned an MSE Academic Advisor. Advising appointments are your opportunity to plan your academic career and track your academic progress. You should meet with your advisor at least once a semester, to plan your courses for your next semester.

When planning for your advising meeting, you should fill out the Robotics Advising Worksheet, located here: <http://lcsr.jhu.edu/robotics-mse-academic-resources/>, which helps chart the progress you have already made and which classes you plan on taking.

NOTE: You are **required to bring a completed Advising Worksheet** (along with any questions you have for your advisor) to each and every advising meeting; advisors reserve the right to refuse to meet with you or release your hold until you have completed this form. This means that you **must select all courses in advance of your first semester**. Of course, as time goes on you may end up selecting different courses for future semesters, but planning ahead is crucial to the success of your program.

These are some best practices for preparing to get the most out of your advising process:

1. Read this advising manual cover to cover.
2. Make a list of courses of interest, then introspect in to SIS for previous years to know which term (spring / fall) the course is typically offered.
3. Check prerequisites of all courses and make sure to fulfill them before the course of interest.
4. Fill out both tabs (course list and term-by term) in the Advising Worksheet.
5. Repeat 2-4 (revise) every term.

NOTE: In Fall 2017, there was widespread updating of course numbering in order to improve consistency across departments. This makes it somewhat harder to use SIS to perform retrospective analysis because one must use the course NAMES and DEPARTMENTS, not COURSE NUMBERS, for historical purposes.

² Internship Option is pending final review of the Whiting School of Engineering's Graduate Committee.



MSE Essay Advising

In some cases, with the approval of a research advisor, the Essay Option may be used to fulfill the MSE Robotics degree requirements. In the standard Course Option, ten (10) courses must be taken as articulated herein. For the Essay Option, eight (8) courses must be taken, and research must be performed leading to a formal MSE Essay. Degree Track requirements are the same for both the Course and Essay Options.

Primary Robotics MSE Essay / Research Advisor Requirements: Research advisors for all Robotics MSE Essay must be approved in advance by the Robotics MSE Graduate Director.

School of Engineering MSE Essay Advisor Requirement: To partially fulfill the degree requirement, the Essay must be approved and signed by the primary research advisor. If the primary advisor is *not* a robotics faculty member holding primary appointment in the Whiting School of Engineering, a second advisor (who satisfies this requirement) must also read and sign the essay. That secondary advisor must be identified and sign off on the Essay Advisor/Advisee Mutual Work Agreement form.

1. To qualify for the essay option, fill out and submit an Essay Advisor/Advisee Mutual Work Agreement form at least two weeks before the beginning of your research. In the extremely unlikely event that you need to change advisors mid-research, please contact Alison Morrow. **You are not admitted into the essay option until you have submitted an Essay Advisor/Advisee Mutual Work Agreement form, and that form has been approved by the program.**
2. It is recommended that students meet with their essay advisors to develop a timeline for research and essay writing, and that portions of the essay be written as the research proceeds. For example, the introduction, background, and motivation for the research can and should often be written in the very early stages of the research. It is highly recommended that the student and advisor choose a second reader to review the essay. At least one reader must be a primary faculty in LCSR, and have their primary appointment in the Whiting School, or be approved by the Robotics Curriculum Committee.
3. Register for Essay Research classes
 - The correct course is 620.801 Robotics Graduate Research, please register in the section with your research advisor (if you have questions about this, talk to Alison Morrow).
 - *If you are on non-resident status*, sign up for the Non-Resident Course instead: EN.910.600
 - If you have any questions about this requirement, confirm you are signed up for the correct course with [Alison Morrow](#).
4. Your essay must be submitted to your advisor for edits at least four weeks before the Robotics essay submission deadline
5. The final version of the master's essay must be submitted, with the cover page signed by the student's advisor, to the LCSR Academic Staff and EDT (Electronic Theses and Dissertation staff) by the essay completion date. See Alison Morrow for updated deadline information.



MSE Internship Advising

A student may choose to fulfill the Robotics MSE degree requirements with the Internship Option, which requires having secured an internship of at least three months and no more than six months, approval and oversight of a research advisor, and a submitted report at the conclusion of the internship. In the standard Course Option, ten (10) courses must be taken as articulated herein. For the Internship Option, eight (8) courses must be taken, not including any research courses, and research must be performed through an Internship, leading to an Internship Report. Alternatively, a journal publication or a conference paper could be submitted, describing the student's original research conducted during the internship. This paper must have been accepted for publication or published in an archival, peer-reviewed technical journal or accepted for presentation at a peer-reviewed technical conference. The student must be the primary author of the article. Degree Track requirements are the same for all degree options.

JHU Research Advisor Requirements: The research advisor should be a member of the Robotics faculty, as listed in the Robotics Advising Manual. In some unusual cases, exceptions can be made, in which case the research advisor must be a JHU professor holding an appointment in the Whiting School of Engineering. All research advisors for all Robotics MSE internships must be approved in advance by the Robotics MSE Graduate Director.

Students should start the Internship Option process **early**. Identifying an internship and an internship advisor, completing the Internship Mutual Work Agreement, and completing the Internship Agreement take time. You are required to submit the Internship Mutual Work Agreement and the sign Internship Agreement **at least two (2) weeks before the start of the semester of the internship**. It is recommended that you start identifying an internship advisor at least a month before the semester of the internship and begin the paperwork then.

To Qualify for the Internship option:

- Robotics MSE students need to first identify and apply for an internship on their own, and if selected for an internship, then must identify a faculty internship advisor from within the Robotics faculty.
- Submit Internship Mutual Work Agreement to the Academic Staff: fill out and submit an Internship Mutual Work Agreement form at least two weeks before the beginning of the internship, which must be signed by the student, the internship supervisor, the research advisor, and the Robotics MSE Graduate Director. **You are not admitted into the internship option until you have submitted the Internship Mutual Work Agreement form, and that form has been approved by the program.** [The Internship Mutual Work Agreement form can be found here.](#)
- Submit the Internship Agreement to Academic Staff - a legal document to protect the faculty overseeing the internship must also be completed. This document must be signed once every three years, so please check with the Academic Staff to make sure it is necessary before starting the signature process.
 - Here is the JHU Approved Agreement that must be fully signed before the Internship Option can be approved. Download here: [OGC Approved Internship Agreement.9.10.21](#)
 - If the company offering the internship requires negotiations, then please send Alison Morrow the following (your internship supervisor and research advisor should be able to assist in this process):



- The full legal name of the company
- The name of official authorized to sign for the company
- A contact email for the official
- If negotiations are not necessary, send the company signed agreement to Alison Morrow for the JHU signature. Please include the name and email address of the official authorized to sign for the company. Please also rename the file to be the Company Name_date signed.
- **The fully executed document must be included with the Internship Mutual Work Agreement form. The Internship Option will not be approved without both documents.**

Additional Information:

- Students in the internship option are required to have a joint meeting (or teleconference) with their research advisors and internship supervisors (together) at least on a monthly basis.
- Students will be required to apply for and register for the appropriate internship research course (EN.620.802 Robotics MSE Graduate Internship Research, please check with Alison Morrow if you cannot find your advisor's section) **and/or** non-resident status/course.
- All international students need to work with Office of International Services (OIS) for Curricular Practical Training (CPT) approval and will need to additionally register for EN.500.851. Credits for this course will not count towards the degree. Additional details about CPT can be found on the Office of International Services (OIS) website: https://ois.jhu.edu/Immigration_and_Visas/F1_Student/F-1_Training_and_Employment/Curricular_Practical_Training/index.html. Please note that failure to comply with the CPT rules as laid out by OIS can result in loss of your F-1 status.
- Your research report (or article) must be submitted to your advisor for edits at least 4 weeks before the graduation submission deadline. The research report (or article) must be submitted within 4 weeks of the completion of the internship.

The final version of the internship report (or journal article) must be submitted, with the cover page signed by the student's research advisor and internship supervisor, to the Robotics Academic staff by the completion date. See Alison Morrow for deadline information. In cases where the report must be confidential, then both the internship supervisor and the research advisor must read and approve the full report, and a non-confidential summary must be approved and submitted to the Robotics Academic Staff by the essay deadline for graduation.

Graduate Student Annual Reviews

A written review of all master's students is required. The review process includes the opportunity for a student to offer a self-evaluation to discuss with his or her advisor. If the student is completing an MSE Essay, the student is expected to hold an annual review with both the research advisor *and* the academic advisor, to ensure that the student is staying on track on both academics and research.

The Graduate Program Committee has created a review form, found here: <http://lcsr.jhu.edu/robotics-mse-academic-resources/>



Before the second week of class in the Spring semester, usually the first week in February, all master's students must complete this form and discuss it with their advisor. The student and advisor will both sign the review, which must be submitted to the Robotics academic staff.

The greatest benefit of this review will no doubt come from the student–advisor meetings, but the completed reviews are also structured to provide the center with a meaningful measure of the progress that our students are making.

GRADUATION

Academic Deadlines

Students preparing to complete a degree program in a given semester should see Alison Morrow to ensure that all necessary forms and requirements have been completed and submitted *prior* to the academic deadlines for the semester. The deadlines to submit certification material usually fall within the following time periods:

Fall – early October

Spring – early March

Summer – mid-July

Essays deadlines are later – please check with Alison Morrow for current deadlines. Students who have not completed their requirements by the first day of classes must register for the current semester.

To Graduate

1. Submit Intent to Graduate form through SIS by the posted deadline.
2. Fill out the degree checkout sheet, which can be found here: <http://lcsr.jhu.edu/robotics-mse-academic-resources/>.
3. Review with your advisor, who signs the form.
4. Attach a copy of your unofficial transcript to the form.
5. **For combined students only:** attach copies of your undergraduate transcript and your undergraduate checkout sheet to the form.
6. **If you are double counting courses** from another university: attach a copy of the other university's transcript to the form.
7. Return the form to Alison Morrow (alison.morrow@jhu.edu) in 200 Hackerman Hall by the advertised deadline.
8. If you are finishing the essay option, the cover page of the essay must be signed by the student's essay advisor. Copies of the essay must be submitted to Robotics academic staff and ETD (Electronic Theses and Dissertation staff) by the essay completion date, which is advertised here: <http://lcsr.jhu.edu/robotics-mse-academic-resources/>

ETD submission instructions are here: <http://guides.library.jhu.edu/etd>

Note that there is a fee to submit your essay.



ACADEMIC POLICIES

Please read through all of the policies. It is your responsibility to adhere to all requirements and policies.

Academic Performance Requirements

Course Grade Requirement: A course is satisfactorily completed if a grade from A+ to B- is obtained. Up to one C+, C, or C- can be counted toward the degree requirements. A grade of D or F or a second grade below B- results in probation. A second D or F, or a third grade below B- typically results in termination from the program. Any exceptions are rare and must be approved in writing by both the student's advisor and the Director of Education.

Audit Courses

Students may audit courses with the approval of their advisor. Credit hours from courses that are audited do not count towards degree requirements or towards full-time status. The Robotics program follows all standard WSE policies regarding auditing: <https://engineering.jhu.edu/education/graduate-studies/graduate-academic-policies-procedures/> (Information under Homewood Grade and Registration Change Guidelines.) This includes: "Changing a course registration from "Audit" [student receives no letter grade] to "Credit" [student receives letter grade], or from "Credit" to "Audit" is permissible during the Office of the Registrar's official add/drop dates. Registration changes beyond this deadline are not permissible. Changing a final grade ("A" through "F", "Pass"), "Incomplete" grade, "In-Progress" grade or "Missing" grade to "Audit" is not permissible at any time."

Double Counting

Standard WSE policy and limitations on double counting apply:

<https://engineering.jhu.edu/education/graduate-studies/graduate-academic-policies-procedures/>.

Below is a basic description of the double-counting policy, for information purposes only; the official WSE policy is on the website, and the Robotics M.S.E. program adheres to that policy.

Coursework applied to a bachelor's degree:

Students either in a WSE combined (bachelor's/master's) program or seeking a WSE master's degree after having earned a WSE or Krieger School of Arts and Sciences bachelor's degree may double-count two (2) courses (400-level or higher) to both programs with the permission of the master's academic advisor. WSE master's degree candidates may not double-count courses applied to a bachelor's degree earned at a different institution.

Coursework not applied to a bachelor's degree:

For students who are either in a WSE combined bachelor's/master's degree program or have already earned a Whiting School of Engineering or Krieger School of Arts and Sciences bachelor's degree and are seeking a WSE master's degree, any graduate-level coursework (as defined by the WSE graduate program) not applied to the undergraduate degree may be applied to the graduate degree, regardless of when that course was taken (i.e., before or after the undergraduate degree has been conferred) with the permission of the master's academic advisor.



Note: If you are planning on double counting any courses (e.g. If you are a combined student who took graduate courses while still an undergraduate at JHU), it is your responsibility to understand the double counting policy. Make sure to read the policy, and if you have any questions, contact the Academic Staff in Robotics.

Duration (Time to Completion Limit)

Typical time to completion is 1.5 to 2 years, depending on student pace. Students must complete degree within 5 years from matriculation in the M.S.E. program. A university-approved leave of absence does not count toward this limit. Please be aware that student visas granted by the US government to international MSE students typically have a maximum duration of two years.

Ethics

Unethical behavior can lead to a student's expulsion from the program. Graduate students are therefore expected to be aware of what actions constitute unethical behavior. For example, students must submit work that represents their own efforts. Whenever ideas or results are drawn from other sources, those sources must be cited in the submitted or presented work. **Unless otherwise explicitly permitted by the instructor for that course, students must not collaborate or discuss any assignments prior to submission of the work.** Students must be aware of and adhere to the ethical issues associated with the use of, and in particular the duplication of computer software and must abide by the rules of use set by the developer.

Please consider the following, which has previously been published on the Whiting School of Engineering Academic Affairs website: "An ethical campus fosters a positive sense of community and trust, while unethical actions and attitudes breed suspicion, cynicism, and negativity. Johns Hopkins University strives to be a community in which honesty and respect are valued and upheld, and in which all members of the community uphold the highest degree of ethical conduct.

"Academic ethics is the responsibility of every student, faculty member, and staff person at Johns Hopkins University. You must take the time to learn about what is ethical and what is not - ignorance of ethical rules is not an excuse for cheating. If you see a violation take place, it is your responsibility to report it.

"Every class you take at Hopkins should address ethics, and some activities that are allowed in one class may not be allowed in another class. If you are not sure if an action is ethical for a particular class, e.g. working in a group on homework, read the syllabus carefully and ask your professor."

Examples of Academic Misconduct:

Cheating	Plagiarism
Reusing Assignments	Improper Use of the Internet
Improper Use of Electronic Devices	Unauthorized Collaboration
Alteration of Graded Assignments	Forgery and Falsification
Lying	Facilitating Academic Dishonesty
Unfair Competition	

Note: Unauthorized uploading and downloading of course materials from online sites (like CourseHero, Quizlet, OPAPapers, etc.) is considered academic misconduct.



Information about academic policies of the Whiting School of Engineering can be found at <http://homewoodgrad.jhu.edu/academics/policies/>. Please read it.

Graduate Research Courses

Coursework Option

No more than one 1-semester graduate research course (e.g. 620.801 Robotics Graduate Research) may be counted toward degree requirements. To substitute for a class, the graduate research course must be at least 3 credits. The course must be taken for a letter grade. In some exceptional cases, when the offering department of the course only permits pass/fail, and with the written permission of the academic advisor, the course may be counted towards degree requirements.

Research Essay/Internship Option

While a student may be required to sign up for graduate research courses while working on the master's essay/internship, these research courses may not count towards the 8 required courses for the Research Essay/Internship Option.

Laboratory Safety

Lab Safety is the responsibility of all who use, maintain, or visit the labs within LCSR. Laboratory researchers are responsible for working with the principal investigator to become familiar with the appropriate hazard information and safety policies before performing any work.

The JHU Department of Health, Safety and Environment maintains a website to ensure updated information on policies, issues, and concerns are available to all. Visit <http://www.hopkinsmedicine.org/hse> to view directives concerning Safety Responsibilities and Policies, Environmental Monitoring, Fire Safety, Chemical Safety, Laboratory Safety, and Radiation Safety.

Please also visit the Whiting School's Lab Safety page at <http://labsafety.jhu.edu/> for important information.

For each lab, a Principal Investigator (PI) is assigned. That person is responsible for the safe operation of the lab, training on all chemicals in the work area, the training of the persons on the equipment within the lab, and is a ready source to answer any questions on a specific lab with regards to its operation and all safety aspects. The PIs for each lab are listed on the entrance door to each lab.

Notice of Non-Discriminatory Policy

The Johns Hopkins University admits students of any race, color, sex, religion, national or ethnic origin, handicap or veteran status to all of the rights, privileges, programs, benefits and activities generally accorded or made available to students at the University. It does not discriminate on the basis of race, color, sex, religion, sexual orientation, national or ethnic origin, handicap or veteran status in any program or activity, including the administration of its educational policies, admission policies, scholarship and loan programs, and athletic and other University-administered programs. Accordingly, the University does not take into consideration personal factors that are irrelevant to the program involved.



Questions regarding access to programs following Title VI, Title IX, and Section 504 should be referred to the Affirmative Action Officer, 205 Garland Hall, 410-516-8075.

Residency Requirements

Once students begin their graduate course of study toward a degree, they must complete a minimum of two consecutive semesters of registration as a full-time, resident graduate student. To qualify as a resident student, the student must be present on campus and working toward fulfilling the requirements for the degree. Complete information is available here:

<http://homewoodgrad.jhu.edu/academics/graduate-board/new-grad-board-residency-page/>.

Information about part-time status can be found here: <https://e-catalogue.jhu.edu/engineering/full-time-residential-programs/graduate-policies/academic-policies/#enrollmentstatusetext>. In most cases, students can only be part-time in their final semester, with approval of the program and OIS (when appropriate). If you have any questions, please contact Alison Morrow.

Transfer Courses

Standard WSE policy and limitations on M.S.E. transfer credits apply

(<https://engineering.jhu.edu/education/graduate-studies/graduate-academic-policies-procedures/>) In addition, use of each transfer course toward satisfaction of a specific Robotics M.S.E. degree requirement must be approved in writing by both the student's academic advisor and the Robotics M.S.E. Graduate Director.

WSE Engineering Management Courses

Two (2) 1.5 credit hour courses taken for credit (i.e. a letter grade) may count towards one class of the MSE degree elective requirements if they are pre-approved in writing by the student's academic advisor.

WSE Engineering for Professionals (EP) Courses

Up to two (2) EP courses may count toward the MSE degree elective requirements if they are pre-approved in writing by the student's academic advisor.

Additional policies

Whiting School of Engineering:

<https://engineering.jhu.edu/education/graduate-studies/graduate-academic-policies-procedures/>

Homewood Graduate policies and resources:

<http://homewoodgrad.jhu.edu/>

Course Catalog:

<http://e-catalog.jhu.edu/>



RESOURCES

Center for Leadership Education

The Center for Leadership Education provides many classes in engineering management, English as a second language, and professional communication. While these courses will not count towards the Robotics MSE, they can be useful. Please note: these classes will end up on your transcript, so the grades are important.

More information can be found here: <http://engineering.jhu.edu/cle/programs-minors/>

Financial Aid

The Office of Student Financial Services has other financial aid sources available, including research assistantships and some fellowships. Any enrolled or accepted graduate student who is a U.S. citizen, U.S. permanent resident, or eligible non-citizen may apply for federal and state financial aid. Sources of aid, eligibility requirements, applications, and other information are available at <http://www.jhu.edu/finaid/grads.html>.

Graduate Student Organizations

Johns Hopkins has many student organizations. A list of some that are specifically geared to graduate students can be found here: <http://homewoodgrad.jhu.edu/life-at-hopkins/graduate-student-organizations/>

In addition, the Graduate Representative Organization (GRO) can be found here: <http://studentaffairs.jhu.edu/gro/>. The GRO maintains a list of student groups, which can be found here: <http://studentaffairs.jhu.edu/gro/clubs-groups/list-of-groups/>

Information Technology

The Information Technology Department at Johns Hopkins, whose web site is located at <http://it.jhu.edu> is the online resource for all IT-related information. Their primary focus is to support the missions of the Johns Hopkins Institutions and provide technology solutions for faculty, staff, patients, and students in support of teaching, research, and patient care.

This Web site serves as a repository for all IT-related information at Johns Hopkins. You will find a lot of useful information within this site, including an overview of the IT Organization, its projects and services, support for applications and general questions, and news about emerging technologies and strategic imperatives.

International Office

The International Office can be emailed at ois@jhu.edu and their website is ois.jhu.edu. Please reach out to them with any visa related questions, including questions about Curricular Practical Training (CPT) and Optional Practical Training (OPT). When filing OPT forms, please make sure to inform your academic advisor of the following:

- Degree
- Field of study



- Date of completion (this should be the date degrees are conferred, not the end of classes)
- Whether the student has completed coursework and is working on thesis

Libraries

The JHU Libraries are extensive, both on-ground and online. The Sheridan Libraries, on the Homewood campus, include quiet room, group study rooms, and a café. Library resources can be found here:

<http://www.library.jhu.edu>.

Security

While the Hopkins Security Department provides ample and appropriate security to the campus, they remind us that we must play our part. Please exercise common sense when entering and leaving your office, classrooms, and labs.

- Secure your computers, especially laptops!
- Back up your work onto separate disks or systems in case something happens to computer via virus, equipment problems, or theft. The University provides free anti-virus software that can be downloaded from the website at <https://it.johnshopkins.edu/services/network/resnet/antivirus>

Secure your laptop cases or any bag that might be mistaken for a computer bag.

- Lock your car and don't leave any items inside your car in plain sight. Secure them in your trunk or bring them with you.
- Secure your personal items such as your purse, wallet, books, equipment, and your coat or jacket.
- If you see someone suspicious in your lab or office, don't confront the individual; contact Security at 410-516-7777 right away. Your personal safety is most important.
- If you are uncomfortable walking through campus or to your car at night or otherwise are concerned for your safety, the Security department provides escort services to selected locations. Call 410-516-8700 to arrange for an escort.

Student Disability Services

The Office of Student Disability Services (SDS) assists full-time undergraduate and graduate students in the Krieger School of Arts and Sciences and the Whiting School of Engineering with disability concerns, in compliance with the provisions of the Americans with Disabilities Act of 1990 (ADA) and Section 504 of the Rehabilitation Act of 1973. SDS assists the University community in understanding the effects of disabilities and in eliminating the physical, technical, attitudinal and programmatic barriers that limit the range of opportunities for students with disabilities, as well as provides individuals with reasonable accommodations. The SDS maintains and protects the confidentiality of individual records as required by law.

For additional information and to access the services of the SDS office, please visit

<http://web.jhu.edu/disabilities/index.html>, contact them at 410-516-4720 or studentdisabilityservices@jhu.edu, or visit their office in 385 Garland Hall.



Student Employment

The Student Employment Services office offers opportunities for employment for many positions on the campus. They will help you determine your work eligibility. Should you wish to obtain additional employment, please speak with your advisor so you will be able to fulfill the obligations of your education. The Student Employment Services office is located in the basement of Garland Hall, and their website is located at <http://www.jhu.edu/stujob/>.

Writing Center

The Johns Hopkins Writing Center offers individual meetings with experienced tutors, including experts in scientific and engineering writing styles. More information can be found here:
<https://krieger.jhu.edu/writingcenter/>



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